

**BOUNDARY DISPERSION FOR MITIGATING PWM TEMPORAL
CONTOURING ARTIFACTS IN DIGITAL DISPLAYS**

Cross Reference to Related Applications:

Cross reference is made to the following co-pending patent applications, each being assigned to the same assignee as the present invention and the teachings included herein by reference:

PATENT OR SERIAL NUMBER	TITLE	FILING DATE
5,751,379 08/26,719	METHOD TO REDUCE PERCEPTUAL CONTOURING IN DISPLAY SYSTEMS	10-4-96
09/088,644 TI-25996 (Attorney's Docket #)	GLOBAL LIGHT BOOST FOR PULSE WIDTH MODULATION DISPLAY SYSTEMS	HEREWITH

FIELD OF THE INVENTION

The present invention relates generally to digital video display systems, and more particularly to digital display systems utilizing bit-planes for performing pulse width modulation to display digital video data.

BACKGROUND OF THE INVENTION

Binary spatial light modulators are typically comprised of an array of elements each having two states, on and off. The use of pulse width modulation (PWM) is one conventional approach of digitally displaying incoming analog video data, as compared to an analog display such as a cathode ray tube (CRT) based system. PWM typically comprises dividing a frame of incoming video data into weighted segments. For example, for a system that samples the luminance component of incoming video data in 8-bit samples, the video frame time is divided up into 255 time segments or pixel values (2^8-1). Conventionally, the 8-bit samples are formatted with binary values. The most significant bit (MSB) data is displayed on a given element for 128 time segments. In the present example, the

next MSB has a time period of 64 time segments, and so on, such that the next bits have weights of 32, 16, 8, 4, 2 and 1 time segments, consecutively. Thus, the least significant bit (LSB) has only one time segment. All pixel values are comprised of a summation of these weighted bits.

5 In DMD display systems, such as disclosed in commonly assigned U.S. Patent 5,278,652 entitled "DMD Architecture and Timing for Use in a Pulse-Width Modulated Display System", the teachings of which are incorporated herein by reference, light intensity for each pixel is typically displayed as a linear function of the pixel digital codes. For an 8-bit binary code, 0 is no light, 255 is peak light,
10 and 128 is midscale light. Codes between 0 and 255 form a grayscale in each color. This grayscale sets the image resolution for the system by defining the number of discrete levels of light that can be produced for each color; i.e. red, green and blue. Pulse width modulation (PWM) schemes used to control the mirrors conventionally modulate the mirrors using bit-planes having weights
15 based on powers of two. For example, 20 us, 40 us, 80 us, 160 us, 320 us, 640 us, 1280 us, and 2,560 us are used to define the mirror on-times for the 8 bit-planes needed for 8-bit video where 5.5 ms is available per color. Light is transmitted to the display screen as black for the bit-plane of a pixel which is logic 0 or at full brightness during a bit-plane which logic 1. Since the on-times for bit-planes vary,
20 this results in PWM over a frame period. The viewer's eyes integrate the modulated light so that gray levels are formed and perceived.

A problem arises when using the PWM technique because the light is displayed in series of discrete burst during each frame. The shifts in ordering of these discrete bursts, as the displayed graycodes vary, generate artifacts in some
25 images. For adjacent pixels, where major bit transitions take place, the sudden change in the ordering (and therefore time phase) of the discrete light burst within a frame causes noticeable pulsations in images upon viewing. Viewer's eyes integrate the out of phase ordering of mirror modulation, for adjacent pixels, to create the pulsations. These pulsations are referred to as PWM temporal
30 contouring (hereafter referred to as simply PWM contouring), shown in Figure 1

because they create apparent contours in images that are time-varying. In commonly assigned U. S. Patent 5,619,228 entitled "Method for Reducing Temporal Artifacts in Digital Video Systems", there is disclosed one method of mitigating PWM contouring, the teachings of which are incorporated herein by reference.

PWM contouring can most clearly be seen on a grayscale ramp that goes horizontally across the screen. Here, vertical pulsations are seen at many major bit transitions when a viewer's eyes are scanned horizontally across the screen. When a viewer's eyes scan, the eyes integrate light only briefly over any given part of the screen. The viewer's scanning eyes catch the transmitted light for adjacent pixels out of time phase and pulsations are seen on the screen.

At normal viewing distance, PWM contouring for two adjacent pixels is difficult or impossible to resolve. However, in real images, boundary conditions often exists where many pixels are spatially bunched together with codes near each other (a sky scene for example). If these codes have clusters that cross a major bit transition, while others don't, PWM contouring will occur.

It is desirable to display data on a digital display, such as a DMD, with reduced PWM contouring artifacts without increasing system bandwidth.

SUMMARY OF THE INVENTION

The present invention achieves technical advantages by using boundary dispersion to selectively offset nominal pixel values alternately between a positive offset and a negative offset, repeatedly over a sequence of 2 displayed frames, whereby the average value of the two offset values over 2 displayed frames, as seen by the viewer, is equal to the nominal pixel value. For purpose of clarity the two frame sequence described below refers to two subsequent frames of source video data; however, the sequence can also be comprised of subframes within one frame of source video data. The chosen offset varies as a function of the nominal pixel value, the pixel spatial location on the screen, and pixel temporal location in time. The set of offsets is applied to pixel values is varied over a repeating 2-

frame sequence. Selected offsets are applied to pixel values within each frame as a function of spatial location on the DMD, and which of the 2 frames is being displayed. Within one frame, any given pixel value is offset by some amount above its correct value, and offset the same amount below its normal value in the
5 next frame. Alternatively, the given pixel value is offset below its normal value in the first frame, and then offset above its normal value in the next frame. In either case, the average pixel value over the 2 frames, as perceived by the viewer, is equal to the nominal pixel value. The same is true of all pixels displayed on the DMD where an offset is used.

10 Boundary dispersion offsets certain pixel values from their nominal values in each frame according to preplanned spatial patterns. The spatial pattern used is dependent upon the value of the pixel codes. In each spatial pattern, some pixel values get a positive offset and some get a negative offset. In the next frame, an inverse set of offsets are used so that all pixels average to their nominal values
15 over the consecutive 2-frame sequence.

A cluster of pixel codes at or near the transition of a major bit (e.g.8,16,32,64,128) use the offsets so that some pixels have a major bit set, and some without. Adjacent clusters of pixels, where one cluster contains pixels below the major bit and others contain pixels above the major bit, have the bit transition
20 boundary dispersed. PWM contouring reduction is the result. The offsetting of some pixels positive and some negative in any given frame according to the spatial pattern also prevents any potential flicker artifacts that may be introduced by offsetting pixel codes over 2 frames.

A checkerboard pattern for a 2-frame sequence is one predefined pattern
25 used to a disperse bit transition spatially around a bit transition boundary, for instance, the bit B5, which corresponds to the value of 32. Areas of the screen around this bit transition, for instance, codes 26 through 29, use more complex 2-frame patterns. The added complexity of these patterns is needed to control the density of pixels that have a major bit, i.e. B5, set in any given frame. A balance
30 is struck between reducing PWM boundary artifacts and new artifacts introduced

within a spatial area having a given code. This is because if too many (or too few) pixels have the major bits set, i.e. B5, within an area using a given code, temporal noise can result in this area. The patterns are properly defined so that the contouring artifacts within a code (intra-code) are much less objectionable than the major bit transition boundaries (inter-code boundaries). By use of a particular pattern, for instance the checkerboard pattern, the spatial patterns have pixels with and without the major bits set are packed so spatially tightly that the intra-code contouring is not resolvable by a viewer at normal viewing distance. Since the PWM contouring is dispersed over a larger area, the overall temporal artifacts seen in the image are greatly reduced.

BRIEF DESCRIPTION OF THE DRAWINGS

Figure 1 is an illustration of the source of PWM temporal contouring;

Figure 2 is an illustration of the PWM temporal contouring reduction using boundary dispersion according to the preferred embodiment of the present invention, whereby a checkerboard pattern is utilized to disperse a major bit transition, such as the B5 bit transition, spatially around the major bit transition boundary;

Figure 3 is an illustration of an adaptive version of the algorithm of the present invention that employs spatial patterns at and near areas of the screen having major bit transitions, whereby large clusters of pixel values interface one another along a boundary; and

Figure 4 shows a block diagram for implementing boundary dispersion logic according to the present invention, the boundary dispersion being performed by spatially identifying pixels on the DMD based on row and column, as well as identifying which frame of the 2-frame temporal sequence the pixel value is associated with, i.e. frame 1 or frame 2, whereby the correct offset is added or subtracted to each pixel value in a particular spatial-temporal assignment.

DESCRIPTION OF THE PREFERRED EMBODIMENT

Referring now to Figure 2, there is illustrated PWM temporal contouring reduction using boundary dispersion according to the preferred embodiment of the present invention. Many of the pixel code values input to the DMD formatting electronics results in this value being offset from its nominal value when displayed on the DMD. The offset varies as a function of the pixel digital code, the pixel spatial location on the screen, and pixel temporal location in time. The set of offsets applied to pixel values is varied over a repeating 2-frame sequence. Selected offsets are applied to pixels within each frame as a function of spatial location on the DMD and which of the 2 frames are being displayed.

Within one frame, any given pixel is offset by some amount above or below its correct value, and offset below or above, respectively, its normal value in the next frame. The average value over the 2 frames, as seen by the viewer, is equal to the nominal pixel value. The same is true of all pixels displayed on the DMD where an offset is used.

Boundary dispersion offsets pixels from their nominal values in each frame according to preplanned spatial patterns. This spatial pattern used is dependent on the value of the pixel code to disperse the pixels that have a major bit transition. In each spatial pattern, some pixels get a positive offset and some get a negative offset. In the next frame, an inverse set of offsets are used so that all pixels average to their nominal value.

A cluster of pixel codes at or near the transition of a major bit (e.g. 8, 16, 32, 64, 128) will have some pixels with this major bit set, and some without. Adjacent clusters of pixels, where one cluster contains pixel values below the major bit and the other cluster contains pixel values above the major bit have the bit transition boundary dispersed. PWM contouring reduction is the result.

As shown in Figure 2, there is illustrated spatial patterns implementing boundary dispersion, shown at top for areas of the screen using code 31 or code 32. A 2-frame checkerboard pattern is used to disperse the B5 bit transition spatially around the bit transition boundary. Areas of the screen having codes 26 - 29 use

more complex 2-frame patterns, shown in the middle checkerboard pattern. The added complexity of these patterns is needed to control the density of pixels that have B5 set in any given frame. A balance is struck between reducing PWM boundary artifacts and the new artifacts introduced within a spatial area having a given code. If too many (or too few) pixels have B5 set, within an area using a given code, temporal noise can result in this area. This temporal noise is actually a form of PWM contouring, except now the contouring occurs on the screen within areas having the same pixel codes, rather than at major bit boundaries between clusters of pixels on the screen.

Since the patterns are properly defined, the contouring artifacts within a code (intra-code) are much less objectionable than at major bit transition boundaries (inter-code). In fact, for most patterns (like the checkerboard pattern) the spatial patterns having the pixels with and without the major bit set are packed so tightly that the intra-code contouring is not resolvable by a viewer at normal viewing distance. The fact that adjacent pixels have transmitted light out of time phase cannot be resolved.

As illustrated in Figure 2, the transition between codes 31 and 32 have the PWM contouring at this boundary dispersed to within codes 31 and 32 rather than having a clearly defined boundary. Since the PWM contouring is dispersed over a larger area, the overall temporal artifacts seen in the image are greatly reduced.

Figure 3 illustrates an adaptive version of the algorithm that only employs the spatial patterns at and near areas of the screen having major bit transitions. This approach allows for any intra-code artifacts created by the present invention to be eliminated for areas of the screen not needing boundary dispersion invoked.

Referring back to Figure 2, it can be seen that for other pixel values further away from the transition boundary, such as pixel values 26, 27, 28 and 29, using boundary dispersion sets the major bit during one frame, but not the next frame to help control the density of pixels that have B5 set in any given frame. For a pixel code of 29, for instance, a pixel code of 33 ($29 + 4$) is displayed during frame 1, with a pixel code of 25 ($29 - 4$) being displayed the frame 2. For a pixel code of

27, a pixel code of 33 ($27 + 6$) is displayed the first frame, with a pixel code of 21 ($27 - 6$) being displayed the next frame. Thus, a major bit is set one frame, but not the next.

As shown in Figure 2, the checkerboard pattern takes into account the spatial location of the pixels in the display. For instance, for a pixel identified at 20 in column 1, row 1, the lower value is displayed during frame 1, and the higher value being displayed in frame 2. For an adjacent pixel such as the pixel identified at 22, being in row 1 column 2, the higher value is displayed during frame 1 and the lower value being displayed frame 2. Again, the average over this 2-frame sequence is the nominal pixel value.

Still referring to Figure 2, to display a pixel value of 28, for instance, 25% of the pixels are set up to use the MSB B5. As shown, every other row of pixels utilizes the MSB B5 in one frame, and not the next. In row 2 and row 4, for instance, the MSB is never used, although the pixel value is offset a lower amount i.e. ± 2 , for these rows to help minimize temporal contouring. For instance, pixel 24 will have a value of 30 during frame 1, and 26 the next frame. The adjacent pixel in row 2 column 2, however, will have the lower value of 26 during frame 1 and the higher value of 30 the next frame. In either instance, pixel 24 never has the MSB B5 set. The MSB is only set in the odd rows of pixels for pixel values that are closer to a bit transition, i.e. 26, 27, 28, and 29.

For even lower values of pixel codes that are further away from a bit transition, i.e. pixel codes 24 and 25, none of the pixels use the MSB B5, however, the value of the pixel code is dithered from frame to frame slightly, i.e. ± 2 , to help achieve acceptable temporal contouring mitigation.

Referring again to Figure 3, there is shown how a section or cluster of pixels are displayed as a function of the source pixels for the same cluster. If there is a boundary defined by a cluster of pixel values i.e. 29 and 30, using the boundary dispersion process of the present invention the pixel values of 30 will be either ± 2 or ± 4 , depending on the frame being displayed. However, the pixel values of 29 will be offset either ± 4 or ± 2 , depending upon the frame being displayed. Again,

TABLE 1

Code	Offsets	Pattern Type
255	+/-0	None
254	+/-0	None
253	+/-2	Checkerboard
252	+/-2	Checkerboard
251	+/-2	Checkerboard
250	+/-2	Checkerboard
249	+/-2	Checkerboard
248	+/-2	Checkerboard
247	+/-2	Checkerboard
246	+/-2	Checkerboard
245	+/-6,+/-2	25% Crossing
244	+/-6,+/-2	25% Crossing
243	+/-4,+/-2	25% Crossing
242	+/-4,+/-2	25% Crossing
241	+/-2	Checkerboard
240	+/-2	Checkerboard
239	+/-2	Checkerboard
238	+/-2	Checkerboard
237	+/-4,+/-2	25% Crossing
236	+/-4,+/-2	25% Crossing
235	+/-6,+/-2	25% Crossing
234	+/-6,+/-2	25% Crossing
233	+/-2	Checkerboard
232	+/-2	Checkerboard
73	+/-2	Checkerboard
72	+/-2	Checkerboard
71	+/-2	Checkerboard
70	+/-2	Checkerboard
69	+/-6,+/-2	25% Crossing
68	+/-6,+/-2	25% Crossing

67	+/-4,+/-2	25% Crossing
66	+/-4,+/-2	25% Crossing
65	+/-2	Checkerboard
64	+/-2	Checkerboard
63	+/-2	Checkerboard
62	+/-2	Checkerboard
61	+/-4,+/-2	25% Crossing
60	+/-4,+/-2	25% Crossing
59	+/-6,+/-2	25% Crossing
58	+/-6,+/-2	25% Crossing
57	+/-2	Checkerboard
56	+/-2	Checkerboard
55	+/-2	Checkerboard
54	+/-2	Checkerboard
53	+/-6,+/-2	25% Crossing
52	+/-6,+/-2	25% Crossing
51	+/-4,+/-2	25% Crossing
50	+/-4,+/-2	25% Crossing
49	+/-2	Checkerboard
48	+/-2	Checkerboard
47	+/-2	Checkerboard
46	+/-2	Checkerboard
45	+/-4,+/-2	25% Crossing
44	+/-4,+/-2	25% Crossing
43	+/-6,+/-2	25% Crossing
42	+/-6,+/-2	25% Crossing
41	+/-2	Checkerboard
40	+/-2	Checkerboard
39	+/-2	Checkerboard
38	+/-2	Checkerboard
37	+/-6,+/-2	25% Crossing
36	+/-6,+/-2	25% Crossing
35	+/-4,+/-2	25% Crossing
34	+/-4,+/-2	25% Crossing
33	+/-2	Checkerboard
32	+/-2	Checkerboard
31	+/-2	Checkerboard
30	+/-2	Checkerboard
29	+/-4,+/-2	25% Crossing
28	+/-4,+/-2	25% Crossing
27	+/-6,+/-2	25% Crossing
26	+/-6,+/-2	25% Crossing
25	+/-2	Checkerboard
24	+/-2	Checkerboard
23	+/-2	Checkerboard
22	+/-2	Checkerboard
21	+/-6,+/-2	25% Crossing
20	+/-6,+/-2	25% Crossing
19	+/-4,+/-2	25% Crossing
18	+/-4,+/-2	25% Crossing

The larger the pixel value, the more pixel codes adjacent this boundary that have temporal contouring applied.

Referring now to Figure 4, there is shown a block diagram of the present invention. 24-bit data (8 bits per color) is the input from the video source. A degamma function 30 is applied to each RGB color so that the DMD display output matches a CRT response. Since the degamma output is limited to 24 bits, a spatial contouring filter is included that diffuses the 8-bit per color quantization errors for low intensity pixels. The boundary dispersion logic 32 according to the present invention accepts the spatial contouring filter output. The boundary dispersion logic 32 receives signals to identify pixels spatially on the DMD, which signals are provided on signal lines row count ROWCNT and column count COLUMNCNT. A signal is also provided to identify the particular frame of the 2-frame temporal sequence, identified as signal FRAME 1/2. A logic high on this line indicates a FRAME 1, and a logic 0 indicates FRAME 2. The boundary dispersion logic assigns spatial patterns as a function of these signals where offsets are applied to each 8-bit color pixel. The offset values are provided to the boundary dispersion logic 32 so that the correct offset is added or subtracted to each pixel in a particular spatial-temporal assignment, as shown in Figure 2 and illustrated in Table 1. The offsets and spatial-temporal patterns applied by the boundary dispersion logic 32 are also a function of the pixel codes. Table 1 illustrates this. Figure 2 illustrates how the boundary dispersion logic is applied to pixels in a spatial-temporal manner.

The 24 signals from the boundary dispersion logic 32 are input into the DMD data formatting logic 40. The DMD data formatting logic organizes the input data into words which form digital planes of information and then loads them into banks of RAM 42. Data is written to one bank of RAM 40 while the other bank is being continuously read and written to the DMD. Thus, a double-buffer memory is used. The buffers are swapped at each VSYNC which indicates a frame boundary for source pixels.

PIXEL
~~VALUE~~

TABLE													
VALUE												w/Gb	no Gb
		plus				minus						+/-	+/-
0000	16	2				2						0000	2
0001	17	4	7	8		8	7	5	4			0001	2
0010	18	1	2	4	5	4						0010	4
0011	19	2	5	6		5						0011	4
0100	20	6				6						0100	6
0101	21	8	11	12		12	11	9	8			0101	6
0110	22	5	6	8	9	8						0110	8
0111	23	6	9	10		9						0111	8
1000	24	5	8	9		9	8	5				1000	8
1001	25	4	7	8		8	7	5	4			1001	8
1010	26	8				9	8	6	5			1010	6
1011	27	2	5	6		5						1011	6
1100	28	1	4	5		5	4	1				1100	4
1101	29	0	3	4		4	3	1	0			1101	4
1110	30	4				5	4	2	1			1110	2
1111	31	-2	1	2		1						1111	2

Referring now to Table 2, there is shown an alternative embodiment of the present invention to account for any problems that may occur when boundary dispersion according to the present invention is utilized in combination with a global boost algorithm, as disclosed in commonly assigned ^{U.S. Patent Application} ~~patent application~~ Serial Number 09/088,641 identified as Attorney's Docket TI-25996 entitled "GLOBAL LIGHT BOOST FOR PULSE WIDTH MODULATION DISPLAY SYSTEMS" filed herewith, and the teachings of which are incorporated herein by reference.

An example of a problem occurs when boundary dispersion receives an input pixel value of 17. The boundary dispersion algorithm may perform a +/-2 offset on the 17 and output a 19 one frame and a 15 the other frame according to a checkerboard pattern to traverse the PWM bit boundary. The global boost algorithm, as disclosed in the co-pending patent application, then outputs a (16,16+6) pattern for the 19 value, and a (8+6,16) pattern for the 15 value. The problem is that the output will be (16,16) or (16+6, 8+6) depending upon the phase relationship between the boundary dispersion and the global boost checkerboards. These two patterns yield DC PWM output of $(16+16)/2=16$ or $(22+14)/2=18$ depending upon the phase. If it is 16, the output DC PWM has an error of -1 since it should be 17. Furthermore, a DC value of 1 cannot simply be added in global boost or boundary dispersion to offset this error because the result of the +1 will yield other checkerboard conflicts, as well. Note that Table 2, which illustrates codes 16-31 may be repeated to all 256 grayshades.

Though the invention has been described with respect to a specific preferred embodiment, many variations and modifications will become apparent to those skilled in the art upon reading the present application. It is therefore the intention that the appended claims be interpreted as broadly as possible in view of the prior art to include all such variations and modifications.